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SHARING HIGHER-ORDER ADVANCED RESEARCH KNOW-HOW on FINITE VOLUME

Great White

São Félix, Portugal

May 23 - 27, 2016



High-order finite volume method for curved boundaries and non-matching domain-mesh problems

May 23-27, 2016, São Félix, Portugal

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Université de Toulouse



Universidade do Minho

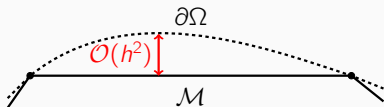
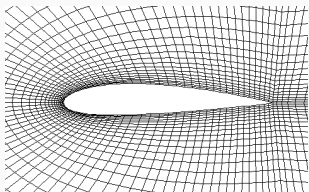
Outline

- ➊ Motivation and Background
- ➋ Problem Formulation
- ➌ Polynomial Reconstruction Machinery
- ➍ ARCH Method
- ➎ Finite Volume Scheme
- ➏ Numerical Benchmark
- ➐ Conclusions and Final Remarks

Motivation and Background



Replacing **curved boundaries** by polygonal edges associated to the mesh provides at most **2nd-order** accuracy



- Isoparametric elements are widely applied for FEM and DG
- Very few methods have been developed in the context of HO-FVM

State-of-art in HO-FVM

- **Ghost cells approach**: add extra cells between the geometric boundary and the computational domain

¹C.F. Ollivier-Gooch and M. Van Altena, A high-order accurate unstructured mesh finite-volume scheme for the advection-diffusion equation, Journal of Computational Physics, (2002).

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- **Ghost cells approach**: add extra cells between the geometric boundary and the computational domain
- **Ollivier-Gooch approach**¹: enforce the BC by constraining the LSM associated to the PR
 - can be **very time consuming** if the LSM matrix has to be updated (moving boundaries/interfaces, tracking interfaces/discontinuities problems)

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New approach: detach the BC conservation from the LSM matrix

- Easier, flexible, more efficient, more elegant

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Problem Formulation

- Poisson's equation and BCs:

$$\nabla^2 \phi = f, \quad \text{in } \Omega$$

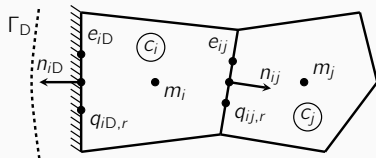
$$\phi = \phi_D, \quad \text{on } \Gamma_D$$

$$\nabla \phi \cdot \mathbf{n} = g_N, \quad \text{on } \Gamma_N$$

$$\alpha \phi + \beta \nabla \phi \cdot \mathbf{n} = g_R, \quad \text{on } \Gamma_R$$

- $\Omega, \partial\Omega = \{\Gamma_D \cup \Gamma_N \cup \Gamma_R\}$ – real domain and its boundary
- $\mathbf{n}$ – unit normal vector to $\partial\Omega$
- ϕ_D – Dirichlet BC
- g_N – Neumann BC
- g_R – Robin BC with coefficients α and β

Generic FV Scheme



- c_i, e_{ij} – cell, edge
- q_i, q_{ij} – quadrature points
- n_{ij} – normal vector

$$\int_{\partial c_i} (\nabla \phi) \cdot n_i \, ds = \int_{c_i} f \, dx \Rightarrow \sum_{j \in \nu(i)} |e_{ij}| \left[\sum_{r=1}^R \zeta_r \mathbb{F}_{ij,r} \right] - \mathbf{f}_i |c_i| = \mathcal{O}(h_i^{2R})$$

- Physical fluxes:

$$\mathbb{F}_{ij,r} = \nabla \phi(q_{ij,r}) \cdot n_{ij},$$

- Source term:

$$\mathbf{f}_i = \sum_{s=1}^S \zeta_s f(q_{i,s})$$

Polynomial Reconstruction Machinery



Non-conservative PR for inner edges e_{ij}

$$\varphi_{ij}(x) = \sum_{0 \leq |\alpha| \leq d} \mathcal{R}_{ij}^{\alpha} (x - m_{ij})^{\alpha}$$

- $\alpha = (\alpha_1, \alpha_2)$, $|\alpha| = \alpha_1 + \alpha_2$, $x^{\alpha} = x_1^{\alpha_1} x_2^{\alpha_2}$
- $\mathcal{R}_{ij} = (\mathcal{R}_{ij}^{\alpha})_{0 \leq |\alpha| \leq d}$ – coefficients (to be determined)

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$$E_{ij}(\mathcal{R}_{ij}) = \sum_{q \in S_{ij}} \omega_{ij,q} \left[\frac{1}{|c_q|} \int_{c_q} \varphi_{ij}(x) \, dx - \phi_q \right]^2$$

- $\tilde{\varphi}_{ij}(x)$ defined with $\tilde{\mathcal{R}}_{ij} = \arg \min_{\mathcal{R}_{ij}} [E_{ij}(\mathcal{R}_{ij})]$

Polynomial Reconstruction Machinery



Conservative PR for Dirichlet boundary edges e_{iD}

$$\varphi_{iD}(x) = \phi_{iD} + \sum_{1 \leq |\alpha| \leq d} \mathcal{R}_{iD}^{\alpha} [(x - m_{iD})^{\alpha} - M_{iD}^{\alpha}]$$

- $\alpha = (\alpha_1, \alpha_2)$, $|\alpha| = \alpha_1 + \alpha_2$, $x^{\alpha} = x_1^{\alpha_1} x_2^{\alpha_2}$
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Polynomial Reconstruction Machinery

- Naive mean-value conservation – 2nd-order!

$$\phi_{iD} = \frac{1}{|e_{iD}|} \int_{e_{iD}} \phi_D(x) \, ds, \quad \frac{1}{|e_{iD}|} \int_{e_{iD}} \varphi_{iD}(x) \, ds = \phi_{iD}$$

$$M_{iD}^\alpha = \frac{1}{|e_{iD}|} \int_{e_{iD}} (x - m_{iD})^\alpha \, dx$$

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- Wise mean-value conservation – Quadrature points on $\partial\Omega$!

$$\phi_{iD} = \frac{1}{|\hat{e}_{iD}|} \int_{\hat{e}_{iD}} \phi_D(x) \, ds, \quad \frac{1}{|\hat{e}_{iD}|} \int_{\hat{e}_{iD}} \varphi_{iD}(x) \, ds = \phi_{iD}$$

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$$M_{iD}^\alpha = \frac{1}{|\hat{e}_{iD}|} \int_{\hat{e}_{iD}} (x - m_{iD})^\alpha \, dx$$

- Wise point-value conservation:

$$\phi_{iD} = \phi_D(p_{iD}), \quad p_{iD} \in \hat{e}_{iD}, \quad \varphi_{iD}(p_{iD}) = \phi_{iD}$$

$$M_{iD}^\alpha = (p_{iD} - m_{iD})^\alpha$$

Polynomial Reconstruction Machinery

- Conservation of Dirichlet BC only
- Coefficients M_{iD}^α are boundary dependent
- ☞ **LSM matrix has to be updated** for...
 - ... moving boundaries/interfaces or dynamic BC in time-dependent and unsteady problems
 - ... optimization problems
 - ... tracking interfaces/discontinuities problems
 - ... etc.
- Ollivier-Gooch method consists in an augmented LSM matrix by constraints rows (equivalent to the wise conservation)

ARCH

Adaptive **R**econstruction for **C**onservation of **H**igh-order



The aim of ARCH is to improve the boundary treatment



The main ideas are...

- ... conserve the HO accuracy
- ... detach the boundary from the LSM matrix
- ... easy handling of moving boundaries
- ... generic treatment of Dirichlet, Neumann and Robin BCs



ARCH for boundary edges e_{iB}

$$\varphi_{iB}(x; \psi_{iB}) = \psi_{iB} + \varphi_{iB}(x)$$

- $\varphi_{iB}(x)$ – non-conservative/naive conservative/wise conservative PR
- ψ_{iB} – free parameter (to be determined)

$$E_{iB}(\mathcal{R}_{iB}; \psi_{iB}) = \sum_{q \in S_{iB}} \omega_{iB,q} \left[\psi_{iB} + \frac{1}{|c_q|} \int_{c_q} \varphi_{iB}(x; \psi_{iB}) \, dx - \phi_q \right]^2$$

- $\check{\varphi}_{iB}(x; \psi_{iB})$ defined with $\check{\mathcal{R}}_{iB} = \arg \min_{\mathcal{R}_{iB}} [E_{iB}(\mathcal{R}_{iB}; \psi_{iB})]$
- ψ_{iB} is a RHS – the LSM matrix remains the same :D

- Generic BC on $\partial\Omega$ to satisfy:

$$g(x; \alpha, \beta) = \alpha(x)\phi(x) + \beta(x)\nabla\phi \cdot n$$

- Dirichlet BC: $\alpha = 1, \beta = 0$
- Neumann BC: $\alpha = 0, \beta \neq 0$
- Robin BC: $\alpha \neq 0, \beta \neq 0$

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$$g(x; \alpha, \beta) = \alpha(x)\phi(x) + \beta(x)\nabla\phi \cdot n$$

- Dirichlet BC: $\alpha = 1, \beta = 0$
 - Neumann BC: $\alpha = 0, \beta \neq 0$
 - Robin BC: $\alpha \neq 0, \beta \neq 0$
- For a given $p_{iB} \in \partial\Omega$, the parameter ψ_{iB} is prescribed such that

$$\alpha(p_{iB})\varphi_{iB}(p_{iB}; \tilde{\psi}_{iB}) + \beta(p_{iB})\nabla\varphi_{iB}(p_{iB}; \tilde{\psi}_{iB}) \cdot n = g(p_{iB}; \alpha, \beta)$$

$$\tilde{\psi}_{iB} = \psi_{iB}^0 - \frac{\mathcal{B}(p_{iB}; \alpha, \beta, \psi_{iB}^0)(\psi_{iB}^0 - \psi_{iB}^1)}{\mathcal{B}(p_{iB}; \alpha, \beta, \psi_{iB}^0) - \mathcal{B}(p_{iB}; \alpha, \beta, \psi_{iB}^0 + \varphi_{iB}^1)}$$

- $\psi_{iB}^0 \neq \psi_{iB}^1$

Finite Volume Scheme

- Numerical fluxes:

- inner edge e_{ij} : $\mathcal{F}_{ij,r} = \nabla \tilde{\varphi}_{ij}(q_{ij,r}) \cdot n_{ij}$
- boundary edge e_{iB} : $\mathcal{F}_{iB,r} = \nabla \tilde{\varphi}_{iB}(q_{iD,r}; \psi_{iB}) \cdot n_{iB}$

- PR and fluxes are linear identities

- Linear residual operator $\Phi \rightarrow G_i(\Phi)$ for vector $\Phi \in \mathbb{R}^I$

$$\mathcal{G}_i(\Phi) = \sum_{j \in \nu(i)} |e_{ij}| \left[\sum_{r=1}^R \zeta_r \mathcal{F}_{ij,r} \right] - f_i |c_i|,$$

$$\mathcal{G}(\Phi) = (\mathcal{G}_i(\Phi))_{i=1,\dots,I}$$

- Free matrix method

- Compute vector $\Phi^* \in \mathbb{R}^I$ solution of $\mathcal{G}(\Phi) = 0$

Numerical Benchmark

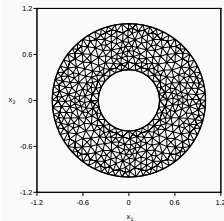
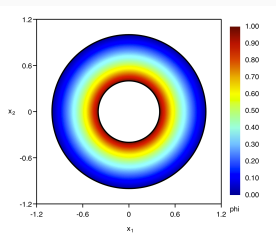
Numerical Benchmark

- Manufactured solution:

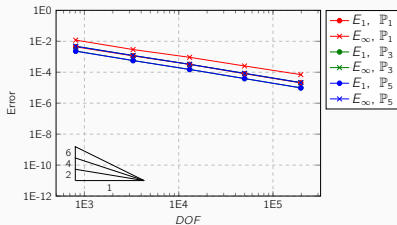
$$\phi(r) = a + b \ln(r)$$

- a, b such that

$$\phi \in [0, 1]$$



Naive PR



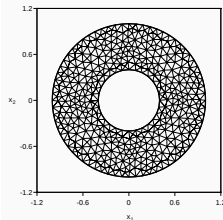
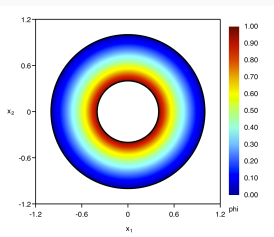
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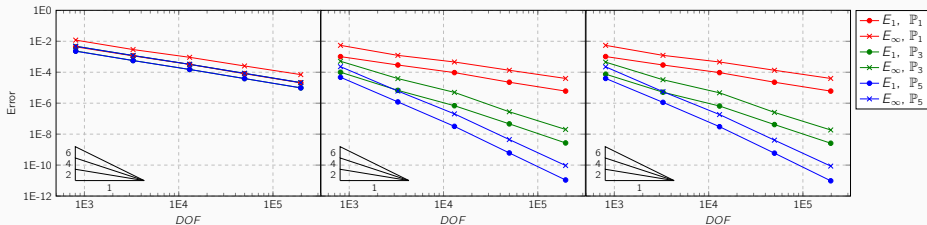
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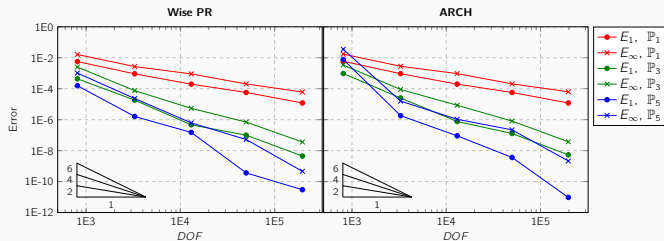
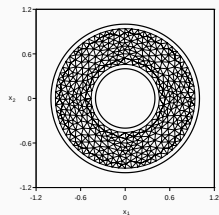
Naive PR

Wise PR

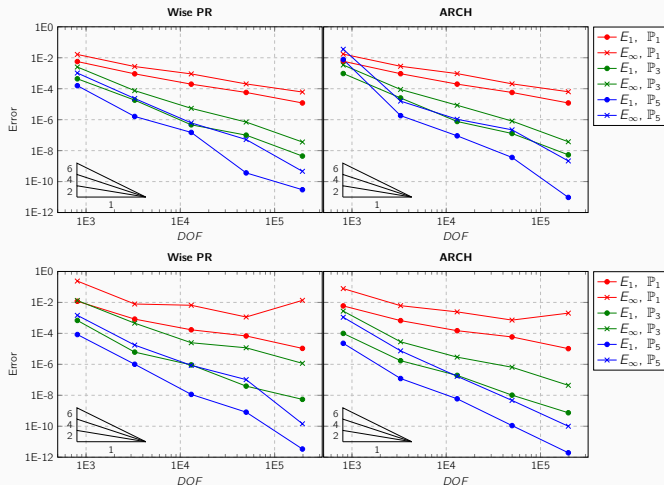
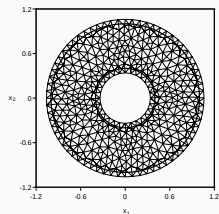
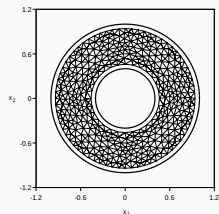
ARCH



Numerical Benchmark



Numerical Benchmark



Numerical Benchmark

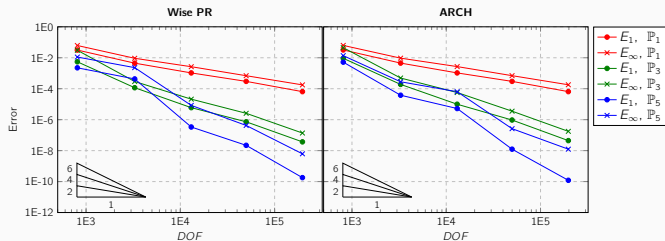
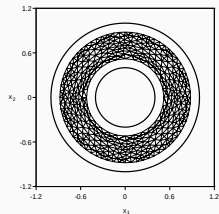
$DOF = 197340$

	P_1		P_3		P_5	
	E_1	E_∞	E_1	E_∞	E_1	E_∞
Naive PR	2.91E-03	9.36E-03	2.91E-03	9.36E-03	2.91E-03	9.36E-03
Wise PR	1.20E-05	6.12E-05	4.45E-09	3.60E-08	2.98E-11	4.60E-10
ARCH	1.20E-05	6.37E-05	5.35E-09	3.74E-08	9.48E-12	2.15E-09

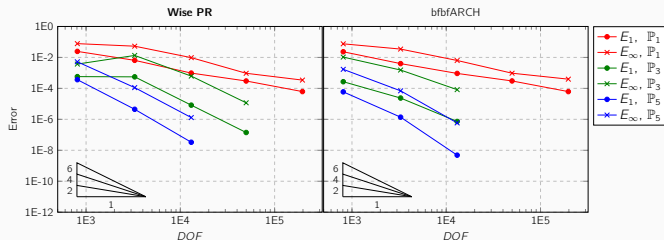
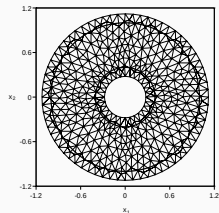
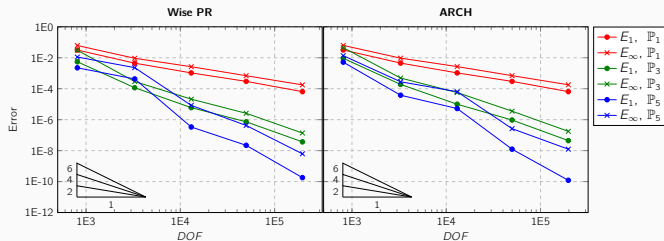
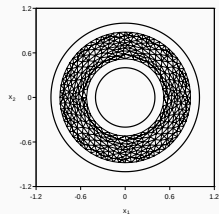
$DOF = 197340$

	P_1		P_3		P_5	
	E_1	E_∞	E_1	E_∞	E_1	E_∞
Naive PR	2.87E-03	9.33E-03	2.87E-03	9.31E-03	2.87E-03	9.31E-03
Wise PR	1.07E-05	1.36E-02	5.45E-09	1.16E-06	3.37E-12	1.44E-10
ARCH	1.03E-05	2.03E-03	7.42E-10	4.40E-08	1.93E-12	1.00E-10

Numerical Benchmark



Numerical Benchmark



Numerical Benchmark

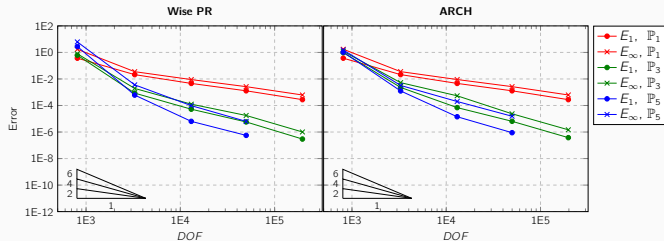
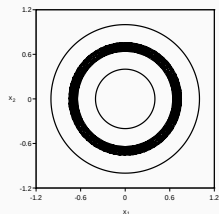
$DOF = 197340$

	P_1		P_3		P_5	
	E_1	E_∞	E_1	E_∞	E_1	E_∞
Naive PR	5.88E-03	1.88E-02	5.88E-03	1.88E-02	5.88E-03	1.88E-02
Wise PR	6.47E-05	1.77E-04	3.68E-08	1.37E-07	1.80E-10	6.22E-09
ARCH	6.48E-05	1.80E-04	4.44E-08	1.76E-07	1.21E-10	1.24E-08

$DOF = 13056$

	P_1		P_3		P_5	
	E_1	E_∞	E_1	E_∞	E_1	E_∞
Naive PR	2.13E-02	7.06E-02	2.12E-02	7.05E-02	2.12E-02	7.05E-02
Wise PR	9.72E-04	9.67E-03	8.25E-06	6.20E-04	3.31E-08	1.30E-06
ARCH	9.24E-04	6.35E-03	7.29E-07	8.27E-05	4.84E-09	5.86E-07

Numerical Benchmark



DOF = 13056

	$\mathbb{P}_1$		$\mathbb{P}_3$		$\mathbb{P}_5$	
	E_1	E_∞	E_1	E_∞	E_1	E_∞
Naive PR	2.13E-02	7.06E-02	2.12E-02	7.05E-02	2.12E-02	7.05E-02
Wise PR	9.72E-04	9.67E-03	8.25E-06	6.20E-04	3.31E-08	1.30E-06
ARCH	9.24E-04	6.35E-03	7.29E-07	8.27E-05	4.84E-09	5.86E-07

Numerical Benchmark

- Γ_I, Γ_E – interior and exterior boundaries

$$\Gamma_I : \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = R_I(\theta; \alpha_I) \begin{bmatrix} \cos(\theta) \\ \sin(\theta) \end{bmatrix}, \quad \Gamma_E : \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = R_E(\theta; \alpha_E) \begin{bmatrix} \cos(\theta) \\ \sin(\theta) \end{bmatrix}$$

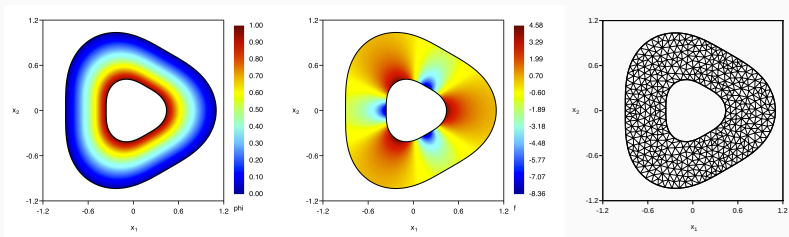
$$R_I(\theta; \alpha_I) = r_I \left(1 + \frac{1}{10} \sin(\alpha_I \theta) \right), \quad R_E(\theta; \alpha_E) = r_E \left(1 + \frac{1}{10} \sin(\alpha_E \theta) \right)$$

- Manufactured solution:

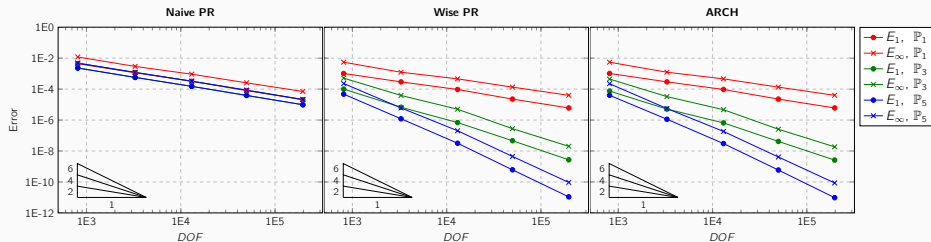
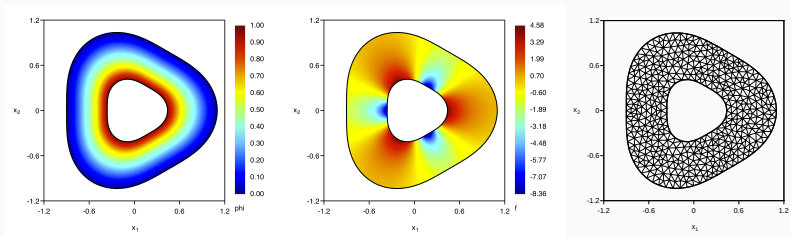
$$\phi(r, \theta) = a(\theta) + b(\theta) \ln(r)$$

- $a(\theta)$ and $b(\theta)$ are chosen such that $\phi \in [0, 1]$ in Ω

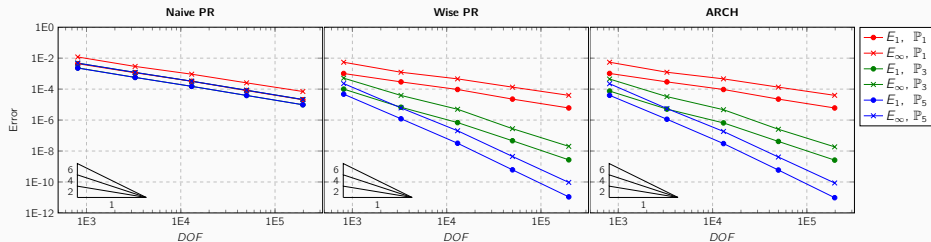
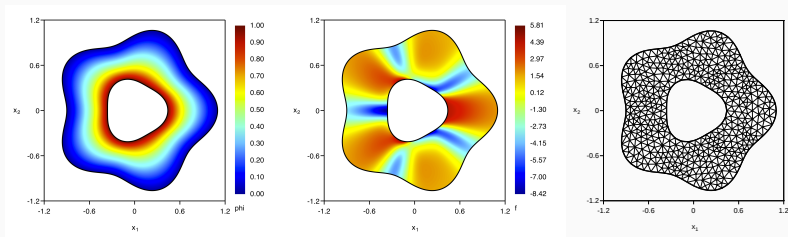
Numerical Benchmark



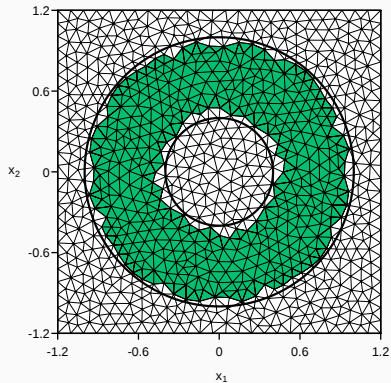
Numerical Benchmark



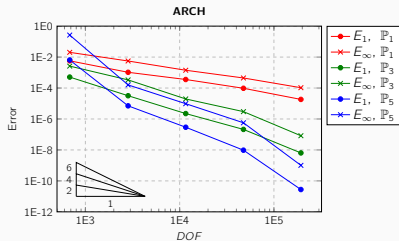
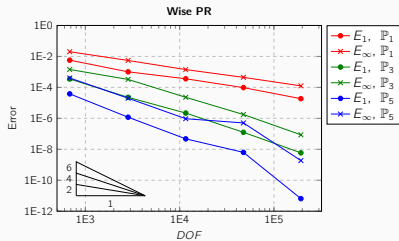
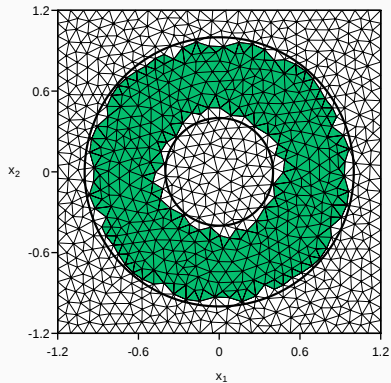
Numerical Benchmark



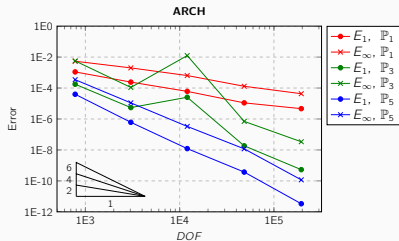
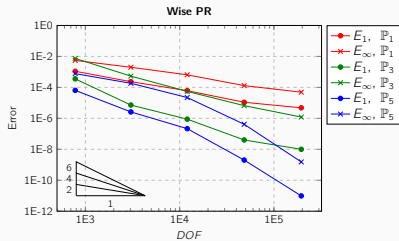
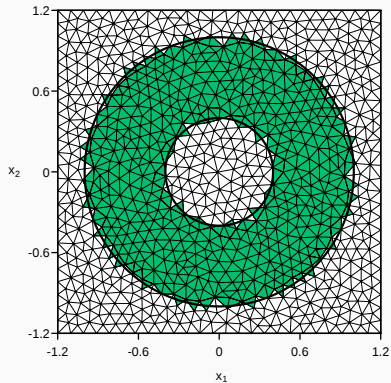
Numerical Benchmark | Mesh Pick-up



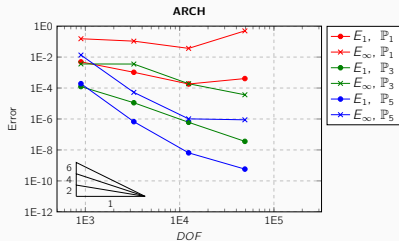
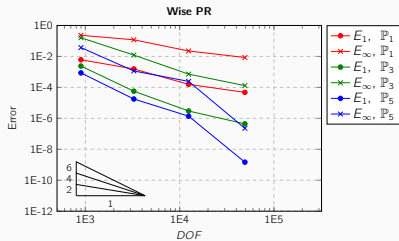
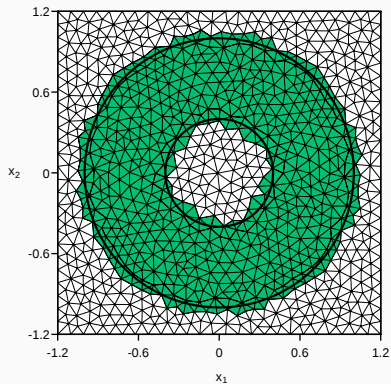
Numerical Benchmark | Mesh Pick-up



Numerical Benchmark | Mesh Pick-up



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Conclusions and Final Remarks

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Obrigado

