

# Stability of finite difference schemes for capillary thin films

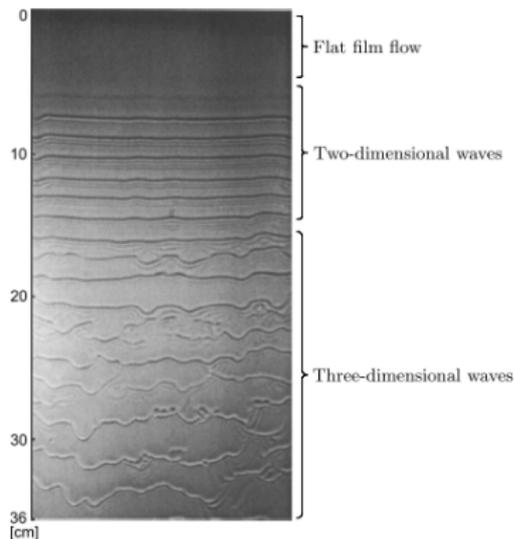
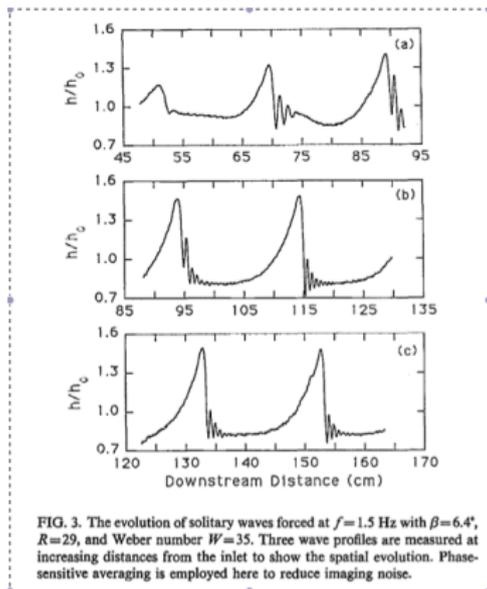
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SHARK FV2015

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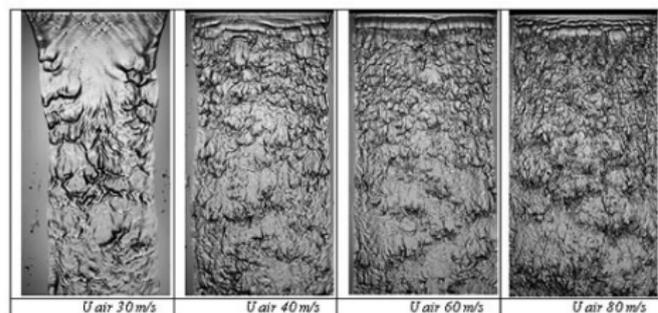
# Introduction: laminar roll waves in laboratory



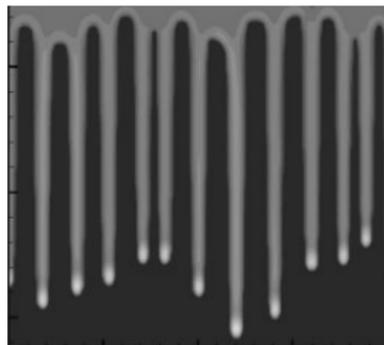
Liu and Gollub experience  
(Phys of Fluids 94)

Photo of 2-d roll-waves  
(Park et Nosoko AIChE, 2003)

# Introduction: falling film in laboratory



Free surface instabilities  
for different gas velocities (ONERA)



# Outline of the talk

- 1 Modeling of thin film flows
  - ▶ Shallow water equations with surface tension
  - ▶ Related models: phase transition
- 2 Stability of difference approximations for shallow water eqs
  - ▶ Von Neumann (linearized) stability
  - ▶ Entropy stability (Schrödinger type formulation)
  - ▶ Two dimensional extension
  - ▶ Implicit strategies
- 3 Numerical simulations
  - ▶ Entropy stability: numerical comparison
  - ▶ Roll-waves: Liu Gollub experiment
  - ▶ Drops: wet/dry fronts

# Thin films flow: shallow water equations I

- **General model:** Navier-Stokes (NS) equations with a free surface
  - ▶ **Unknowns:** velocity  $\vec{u} = (u, w) \in \mathbf{R}^2$ , pressure  $p$ , fluid domain  $\Omega_t = \{(x, z), x \in \mathbf{R}^n, 0 \leq z \leq h(x, t)\}$
  - ▶ **Main issues:** presence of a free surface, study of non linear waves (free surface instabilities)
  
- **Methodology:** under suitable assumptions, derive simpler models
  - ▶ **Aspect ratio:**  $\varepsilon = H/L$ , (characteristic fluid height/characteristic horizontal wavelengthl).
  - ▶ **Reynolds Number:**  $Re = \rho H U / \mu$
  - ▶ **Froude Number:**  $F^2 = U^2 / gH$
  - ▶ **Weber Number:**  $We = \rho U^2 H / \sigma$

## Thin film flows: shallow water equations II

**Definition (consistent models)** Let  $(\vec{u}_\varepsilon, p_\varepsilon, h_\varepsilon)$  be an exact solution of Navier-Stokes equations:  $NS_\varepsilon(\vec{u}_\varepsilon, p_\varepsilon, h_\varepsilon) = 0$ . Define  $q_\varepsilon = \int_0^{h_\varepsilon} u_\varepsilon(\cdot, z) dz$ .

A shallow water model is

- consistent if  $SV_\varepsilon(q_\varepsilon, h_\varepsilon) = R_\varepsilon$  and  $\lim_{\varepsilon \rightarrow 0} \|R_\varepsilon\| = 0$ ,
- of order  $k$  if  $\|R_\varepsilon\| = O(\varepsilon^k)$ : order 1 (1998), order 2 (2001)!

Exemple of first order consistent model (P.N., J.-P. Vila)

$$\begin{aligned} \partial_t h + \partial_x q &= 0, \\ \partial_t q + \partial_x \left( \frac{q^2}{h} + \frac{h^5}{45} + \frac{5 \cotan(\theta) h^2}{12 R_e} \right) &= \frac{5}{6 \varepsilon R_e} \left( h - \frac{3q}{h^2} \right) + \varepsilon^2 We h \partial_{xxx} h. \end{aligned} \quad (1)$$

Remark: in Liu-Gollub experiments,  $\varepsilon^2 We = O(1)$ !

## Related models I: Euler Korteweg equations

**Remark:** neglecting source term, shallow water equations with surface tension are a particular case of Euler Korteweg equations

### Euler-Korteweg equations in conservative variables

$$\begin{aligned}\partial_t \rho + \partial_x(\rho u) &= 0, \\ \partial_t(\rho u) + \partial_x(\rho u^2 + P(\rho)) &= \partial_x \left( \rho \kappa(\rho) \partial_{xx} \rho + (\rho \kappa'(\rho) - \kappa(\rho)) \frac{(\partial_x \rho)^2}{2} \right),\end{aligned}$$

- $\kappa(\rho) = \text{constant}$ ,  $P(\rho) = a\rho^\gamma$ : shallow water type equations
- $\kappa(\rho) = \text{constant}/\rho$ : quantum hydrodynamic (=NLS)
- $\kappa(\rho) = \text{constant}$ ,  $P(\rho) = \frac{\gamma\rho}{1-\rho} - \rho^2$ : Van der Waals gas (phase transition)

### Additional Energy equation

$$\partial_t \left( \rho \frac{u^2}{2} + F(\rho) + \kappa(\rho) \frac{(\partial_x \rho)^2}{2} \right) + \partial_x \mathcal{F}(\rho, u, \partial_x \rho, \partial_x u) = 0$$

## Related models II: water waves

- **General model:** Euler equations with a free surface (incompressible, irrotational)
- **Unknowns:** velocity  $\vec{u} = (u, w) \in \mathbf{R}^2$ , pressure  $p$ , fluid domain  $\Omega_t = \{(x, z), x \in \mathbf{R}^n, -h(x) \leq z \leq \eta(t, x)\}$
- **Main issues:** presence of a free surface, no regularization effects
- **Non dimensional numbers:**  $\sigma = \frac{H}{\lambda}$  (dispersion),  $\varepsilon = \frac{a}{H}$  (nonlinearity)

### Boussinesq equations

$$\partial_t \eta + \partial_x((h + \varepsilon \eta)) = 0,$$

$$\partial_t \bar{u} + \varepsilon \bar{u} \partial_x \bar{u} + \partial_x \eta + \sigma^2 \left( \frac{h^2}{6} \partial_x^2 (\partial_t \bar{u}) - \frac{h}{2} \partial_x^2 (h \partial_t \bar{u}) \right) = O(\varepsilon \sigma^2 + \sigma^4).$$

## Stability of difference schemes: von Neumann stability

- **Remark:** due to the presence of the third order derivative, the energy equation is hardly satisfied in the original formulation
- **A simplified problem:** we check stability for linearized shallow water equations (=Fourier analysis)
- **Interest:** provides necessary and, in practice, sufficient condition of stability

Linearized equations (conservative variables:  $v = (h, q)^T$ )

$$\partial_t v + A \partial_x v = B \partial_{xxx} v, \quad A = \begin{pmatrix} 0 & 1 \\ \bar{c}^2 - \bar{u}^2 & 2\bar{u} \end{pmatrix}, \quad B = \begin{pmatrix} 0 & 0 \\ \bar{\sigma} & 0 \end{pmatrix}.$$

- **Dispersion relation:**  $s(k) = \bar{u} \pm \sqrt{\bar{c}^2 + \bar{\sigma} k^2}$
- **Heuristic CFL condition**  $s(k) \frac{\delta t}{\delta x} \leq 1$ . Here  $s(k) \sim K/\delta x$  then  
**CFL condition:**  $\delta t = O(\delta x^2)$ .

# Von Neumann stability I: formulation of the problem

Stability of difference approximation in the form

$$v_i^{n+1} - v_i^n + \lambda_1 \left( f_{i+\frac{1}{2}}^{n+\theta} - f_{i-\frac{1}{2}}^{n+\theta} \right) = \lambda_3 B \left( v_{i+2}^{n+\theta} - 2v_{i+1}^{n+\theta} + 2v_{i-1}^{n+\theta} - v_{i-2}^{n+\theta} \right). \quad (2)$$

with  $\lambda_k = \delta t / \delta x^k$ , and  $v_i^{n+\theta} = (1 - \theta)v_i^n + \theta v_i^{n+1}$ .

- Lax-Friedrichs scheme:  $f_{i+\frac{1}{2}}^n = \frac{Av_i^n + Av_{i+1}^n}{2} - \frac{1}{2\lambda_1}(v_{i+1}^n - v_i^n)$
- Rusanov scheme:  $f_{i+\frac{1}{2}}^n = \frac{Av_i^n + Av_{i+1}^n}{2} - \frac{\rho(A)}{2}(v_{i+1}^n - v_i^n)$
- Roe scheme:  $f_{i+\frac{1}{2}}^n = \frac{Av_i^n + Av_{i+1}^n}{2} - \frac{|A|}{2}(v_{i+1}^n - v_i^n)$

# Von Neumann stability II: first order accurate schemes

## Definition

We search for solutions of (2) in the form  $v_k^n = \xi^n e^{-ik\theta}$ : a scheme is stable in the sense of Von Neumann if  $|\xi| \leq 1$  for all  $\theta \in [0, 2\pi]$

- **Instability of Roe scheme:** The scheme (2) with Roe type flux and  $\theta = 0$  (forward Euler time discretization: FE),  $\theta = 1$  (backward Euler time discretization: BE) is always unstable: **the equivalent system of PDEs is ill posed** (bad interaction between numerical viscosity and third order terms).
- **Stability of Lax-Friedrichs scheme:**
  - ▶ FE time discretization ( $\theta = 0$ ): stable under cfl condition  $\delta t = O(\delta x^2)$
  - ▶ BE time discretization ( $\theta \geq 1/2$ ): unconditionally stable
- **Stability of Rusanov scheme:**
  - ▶ FE time discretization ( $\theta = 0$ ): stable under cfl condition  $\delta t = O(\delta x^3)$
  - ▶ BE time discretization ( $\theta \geq 1/2$ ): unconditionally stable

## Von Neumann stability III: second order accurate schemes

We use a MUSCL type scheme for space discretization:

$$\begin{aligned}\frac{dv_j}{dt} &= \frac{A}{8\delta x} (v_{j+2} - 6v_{j+1} + 6v_{j-1} - v_{j-2}) \\ &\quad + \frac{\nu_n}{8\delta x^2} (v_{j+2} - 4v_{j+1} + 6v_j - 4v_{j-1} + v_{j-2}) \\ &= \frac{B}{\delta x^3} (v_{j+2} - 2v_{j+1} + 2v_{j-1} - v_{j-2}).\end{aligned}$$

**Remark:**  $\nu_n$  is the numerical viscosity (L-F:  $\nu_n = \delta x^2/2\delta t$ , Ru:  $\nu_n = \rho(A)\delta x$ )

- **Stability of Lax-Friedrichs scheme:**

- ▶ Runge Kutta 2 : stable under CFL condition  $\delta t = O(\delta x^2)$
- ▶ Crank Nicolson ( $\theta = 1/2$ ): unconditionally stable

- **Stability of Rusanov scheme:**

- ▶ Runge Kutta 2 ( $\theta = 0$ ): stable under CFL condition  $\delta t = O(\delta x^{7/3})$
- ▶ Crank Nicolson ( $\theta = 1/2$ ): unconditionally stable

# Well posedness of Equivalent Equations I

Modified or equivalent equation

$$v_t + Av_x = Qv_{xx} + Bv_{xxx} \quad (3)$$

Well posedness with initial data in  $L_p^2$  via Fourier Analysis :

$$v(x, t) = e^{-ix\xi} \hat{v}(t), \quad \frac{d\hat{v}}{dt} = i\xi (A + i\xi Q + \xi^2 B) \hat{v}$$

- well posedness requires eigenvalues  $X$  of  $(A + i\xi Q + \xi^2 B)$  satisfies  $\xi \text{Im}(X) \geq 0 \quad \forall \xi \in \mathbb{R}$
- Scalar continuous case :  $\hat{v}(t) = e^{i\xi(a+\xi^2\bar{\sigma})t} e^{-\xi^2 qt} \hat{v}(0)$  The problem is well posed for initial data in  $L_p^2$  iff  $q > 0$
- System case

$$A = \begin{pmatrix} 0 & 1 \\ \bar{c}^2 - \bar{u}^2 & 2\bar{u} \end{pmatrix}, \quad Q = \begin{pmatrix} q_{11} & q_{12} \\ q_{21} & q_{22} \end{pmatrix}, \quad B = \begin{pmatrix} 0 & 0 \\ \bar{\sigma} & 0 \end{pmatrix},$$

## Theorem

Viscosity matrices are admissible (ie (3) is well posed with initial data in  $L_p^2$ ) iff  $q_{12} = 0$  and  $c^2 \geq \frac{(\bar{u}(q_{11}-q_{22})-q_{21})^2}{(q_{11}+q_{22})^2}$ ,  $q_{11} + q_{22} \geq 0$ ,  $\bar{\sigma} + q_{11}q_{22} \geq 0$

## Well posedness of equivalent Equations II

- Remark : Continuous case with  $q_{11} = 0$ . The problem is ill posed unless  $q_{12} = 0$  and  $c^2 \geq \frac{(\bar{u}q_{22} + q_{21})^2}{q_{22}^2}$ ,  $q_{22} \geq 0$ , and  $\bar{\sigma} \geq 0$
- Proof relies on explicit formulae for Eigenvalues  $X$  : for large  $\xi$  (high frequ.)  $X$  satisfies

$$2X = (2\bar{u} + i\xi(q_{11} + q_{22})) \pm \sqrt{4iq_{12}\bar{\sigma}} \left( \xi^{\frac{3}{2}} + \frac{-i\sqrt{\xi}}{2\xi q_{12}\bar{\sigma}} (q_{11}q_{22} + \bar{\sigma} - q_{12}q_{21}) + O(\xi^{-\frac{1}{2}}) \right)$$

- Modified equation for Godunov/Roe scheme  $Q = |A|$

$$|A| = \begin{bmatrix} \frac{|u-c|(u+c) - |u+c|(u-c)}{(c^2 - u^2)} & \frac{|u+c| - |-u+c|}{2c} \\ \frac{|u+c| - |-u+c|}{2c} & \frac{|u+c|(u+c) - |u-c|(u-c)}{2c} \end{bmatrix}$$

# Entropy stability of difference schemes: new formulation 1

“Entropy” of the Euler-Korteweg system

$$U(\rho, u, \partial_x \rho) = \int \rho \frac{u^2}{2} + F(\rho) + \kappa(\rho) \frac{(\partial_x \rho)^2}{2}$$

- Not an usual entropy (presence of  $\partial_x \rho$ ): reduction of order needed (see C.W. Shu for KdV type equations with DG methods)

- A natural new variable:  $w = \sqrt{\frac{\kappa(\rho)}{\rho}} \partial_x \rho$

- The “entropy”  $U$  now reads  $U(\rho, u, w) = \int \rho \frac{u^2 + w^2}{2} + F(\rho)$ .

- **Remark:** a strategy used for compressible Navier-Stokes equations (“Bresch-Desjardins” entropy) to define new weak solutions.

## Entropy stability of difference schemes: new formulation 2

Euler-Korteweg equations: “Schrodinger type formulation”

$$\partial_t \mathbf{v} + \partial_x f(\mathbf{v}) = \partial_x (B(\rho) \partial_x (\rho^{-1} \mathbf{v})), \quad B(\rho) = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & \mu(\rho) \\ 0 & -\mu(\rho) & 0 \end{pmatrix} \quad (4)$$

with  $\mathbf{v} = (\rho, \rho u, \rho w)^T$ ,  $f(\mathbf{v}) = (\rho u, \rho u^2 + P(\rho), \rho u w)^T$ .

- The Schrodinger formulation is obtained by setting  $\psi = \rho u + i \rho w$  (useful for well posedness: see Benzoni-Danchin-Descombes 2006)
- Setting  $U(\mathbf{v}) = \rho \frac{u^2 + w^2}{2} + F(\rho)$  and  $G(\mathbf{v}) = u(U(\mathbf{v}) + P(\rho))$ :

Energy equation in the new formulation (classic energy estimate)

$$\partial_t U(\mathbf{v}) + \partial_x G(\mathbf{v}) = \partial_x (\mu(\rho) (u \partial_x w - w \partial_x u)). \quad (5)$$

## Entropy stability of difference scheme: definition

We consider the following semi discretized system (setting  $z = \rho^{-1}v$ )

$$\frac{d}{dt} v_j(t) + \frac{f_{j+\frac{1}{2}} - f_{j-\frac{1}{2}}}{\delta x} = \frac{B(\rho_{j+\frac{1}{2}})(z_{j+1} - z_j) - B(\rho_{j-\frac{1}{2}})(z_j - z_{j-1}))}{\delta x^2}. \quad (6)$$

### Definition

The semi-discretized scheme (6) is entropy stable if there exists a numerical flux  $\mathcal{G}_{j+\frac{1}{2}}$ , consistent with the entropy flux in (5), so that

$$\frac{d}{dt} U(v_j(t)) + \frac{\mathcal{G}_{j+\frac{1}{2}} - \mathcal{G}_{j-\frac{1}{2}}}{\delta x} \leq 0.$$

E. Tadmor *Entropy stability theory for difference approximations of nonlinear conservation laws and related time-dependent problems* Acta Numerica (2003)

P.G. LeFloch, J.M. Mercier, C. Rohde *Fully discrete, entropy conservative schemes of arbitrary order*, SIAM J. Numer. Anal. 40 (2002)

C. Chalons, P.G. LeFloch *High-Order Entropy-Conservative Schemes and Kinetic Relations for van der Waals Fluids*, JCP 168 (2001).

## Entropy stability: semi-discrete schemes

### Theorem

Consider the entropy stable scheme

$$\frac{d}{dt} v_j(t) + \frac{f_{j+\frac{1}{2}} - f_{j-\frac{1}{2}}}{dx} = 0, \quad (7)$$

which is a difference approximation of (4) with  $B = 0$ , then the associated difference scheme (6) is an entropy stable difference scheme.

**Proof** The scheme is entropy stable:

$$U_v(v_j(t))^T (f_{j+\frac{1}{2}} - f_{j-\frac{1}{2}}) = \mathcal{F}_{j+\frac{1}{2}} - \mathcal{F}_{j-\frac{1}{2}} + \mathcal{R}_j, \quad \mathcal{R}_j \geq 0$$

Moreover, setting  $\mathcal{K}_j = \langle U_v(v_j(t)); \text{r.h.s of (5)} \rangle$  one has

$$dx^2 \mathcal{K}_j = \mu_{j+\frac{1}{2}} (u_j w_{j+1} - u_{j+1} w_j) - \mu_{j-\frac{1}{2}} (u_{j-1} w_j - u_j w_{j-1})$$

# Entropy stability: fully-discrete schemes I

We consider only first order accurate schemes

## Backward Euler time discretization

$$\begin{aligned} v_j^{n+1} - v_j^n + \lambda_1 \left( f_{j+\frac{1}{2}}^{n+1} - f_{j-\frac{1}{2}}^{n+1} \right) \\ = \lambda_2 \left( B(\rho_{j+\frac{1}{2}}^{n+1}) \left( z_{j+1}^{n+1} - z_j^{n+1} \right) - B(\rho_{j-\frac{1}{2}}^{n+1}) \left( z_j^{n+1} - z_{j-1}^{n+1} \right) \right). \end{aligned} \quad (8)$$

## Forward Euler time discretization

$$\begin{aligned} v_j^{n+1} - v_j^n + \lambda_1 \left( f_{j+\frac{1}{2}}^n - f_{j-\frac{1}{2}}^n \right) \\ = \lambda_2 \left( B(\rho_{j+\frac{1}{2}}^n) \left( z_{j+1}^n - z_j^n \right) - B(\rho_{j-\frac{1}{2}}^n) \left( z_j^n - z_{j-1}^n \right) \right). \end{aligned} \quad (9)$$

with  $f_{j+\frac{1}{2}}$  corresponding to a semi discrete entropy stable scheme.

## Entropy stability: fully discrete scheme II

### Theorem

*Implicit Schemes* Consider the entropy (spatially) stable semi scheme (7) which is a difference approximation of (4) with  $B = 0$ , then the scheme (8) is (unconditionally) entropy stable. There exists  $\mathcal{G}_{j+\frac{1}{2}}^n$  so that

$$U(v_j^{n+1}) - U(v_j^n) + \mathcal{G}_{j+\frac{1}{2}}^n - \mathcal{G}_{j-\frac{1}{2}}^n \leq 0, \forall j, \quad \forall n. \quad (10)$$

### Theorem

#### *Explicit Schemes*

- Explicit scheme with *Lax-Friedrichs flux* is entropy stable with CFL  $\delta t \ll \delta x^2$
- Explicit scheme with *Rusanov flux* is entropy stable with CFL  $\delta t \ll \delta x^3$
- **Question 1:** Two dimensional extension?
- **Question 2:** Implicit strategies (to get rid of CFL conditions  $\delta t = o(\delta x^2)$ )?

## Two dimensional extensions I

### Two-dimensional Shallow Water equations

$$\begin{aligned}\partial_t h + \operatorname{div}(\mathbf{h}\mathbf{u}) &= 0, \\ \partial_t(\mathbf{h}\mathbf{u}) + \operatorname{div}\left(\mathbf{h}\mathbf{u} \otimes \mathbf{u} + \frac{2h^5}{225} \left(\frac{g \sin(\theta)}{\nu}\right)^2 \mathbf{e}_1 \otimes \mathbf{e}_1\right) + \nabla(g \cos(\theta) \frac{h^2}{2}) &= \\ gh \sin(\theta) \mathbf{e}_1 - 3\nu \frac{\mathbf{u}}{h} + \frac{\sigma}{\rho} h \nabla \Delta h.\end{aligned}$$

### Multi-dimensional Euler-Korteweg equations

$$\partial_t \varrho + \operatorname{div}(\varrho \mathbf{u}) = 0, \quad \partial_t(\varrho \mathbf{u}) + \operatorname{div}(\varrho \mathbf{u} \otimes \mathbf{u}) + \nabla p(\varrho) = \operatorname{div} \mathbf{K},$$

$$\mathbf{K} = \left( \varrho \operatorname{div}(K(\varrho) \nabla \varrho) + \frac{1}{2} (K(\varrho) - \varrho K'(\varrho)) |\nabla \varrho|^2 \right) \operatorname{Id}_{\mathbb{R}^n} - K(\varrho) \nabla \varrho \otimes \varrho.$$

## Two dimensional extensions II: (new) extended formulation

Introduce  $\mathbf{w} = \nabla\phi(\varrho)$  with  $\phi'(\varrho) = \sqrt{\frac{K(\varrho)}{\varrho}}$  and  $F'(\varrho) = \varrho\phi'(\varrho)$ .

### Extended formulation of Euler Korteweg equations

$$\begin{aligned}\partial_t \varrho + \operatorname{div}(\varrho \mathbf{u}) &= 0, \\ \partial_t(\varrho \mathbf{u}) + \operatorname{div}(\varrho \mathbf{u} \otimes \mathbf{u} + p(\varrho) \mathbf{I}_{\mathbb{R}^n}) &= \operatorname{div}(F(\varrho) \nabla \mathbf{w}^T) - \nabla((F(\varrho) - \varrho F'(\varrho)) \operatorname{div}(\mathbf{w})), \\ \partial_t(\varrho \mathbf{w}) + \operatorname{div}(\varrho \mathbf{w} \otimes \mathbf{u}) &= -\operatorname{div}(F(\varrho) \nabla \mathbf{u}^T) + \nabla((F(\varrho) - \varrho F'(\varrho)) \operatorname{div}(\mathbf{u})).\end{aligned}$$

Entropy:  $U(\varrho, \mathbf{u}, \mathbf{w}) = \varrho F_0(\varrho) + \frac{\varrho}{2} (\|\mathbf{u}\|^2 + \|\mathbf{w}\|^2)$

$$\begin{aligned}\partial_t U(\varrho, \mathbf{u}, \mathbf{w}) + \operatorname{div}(\mathbf{u}(U(\varrho, \mathbf{u}, \mathbf{w}) + p(\varrho))) &= \operatorname{div}(F(\varrho)(\nabla \mathbf{w} \mathbf{u} - \nabla \mathbf{u} \mathbf{w})) \\ &\quad - \operatorname{div}((F(\varrho) - \varrho F'(\varrho))(\operatorname{div}(\mathbf{w} \mathbf{u}) - \operatorname{div}(\mathbf{u} \mathbf{w}))).\end{aligned}$$

**Remark:** Under suitable compatibility conditions for the discretization of  $\operatorname{div}$  and  $\nabla$  operators, we prove similar energy estimates than in 1d case.

**Restriction:** Entropy quadratic w.r.t.  $\nabla\varrho$ .

## Implicit strategies

- Explicit in time discretization requires a CFL condition  $\delta t = o(\delta x^2)$
- Full implicit in time schemes implies heavy computational costs (especially in 2d).

### Implicit(surface tension)/Explicit (convection) time discretization

$$\begin{aligned} v_j^{n+1} - v_j^n + \lambda_1 \left( f_{j+\frac{1}{2}}^n - f_{j-\frac{1}{2}}^n \right) \\ = \lambda_2 \left( B(\rho_{j+\frac{1}{2}}^{n+1}) \left( z_{j+1}^{n+1} - z_j^{n+1} \right) - B(\rho_{j-\frac{1}{2}}^{n+1}) \left( z_j^{n+1} - z_{j-1}^{n+1} \right) \right). \end{aligned}$$

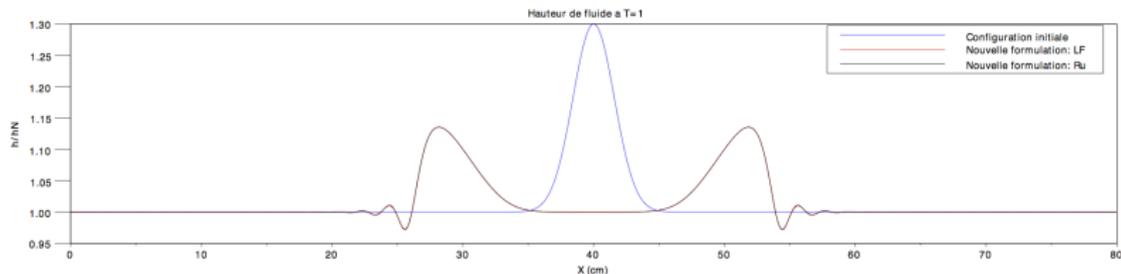
- Stable under CFL condition  $\delta t = O(\delta x)$ .
- Implicit steps amounts to solve (sparse) linear systems.
- Higher order time discretization: IMEx strategies

# Entropy stability: numerical comparison I

- Model: shallow water equations with horizontal bottom

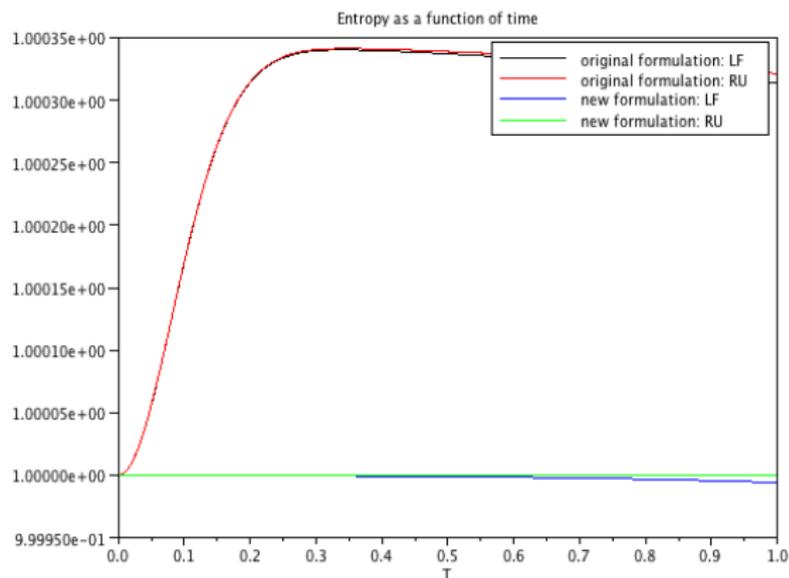
$$\partial_t h + \partial_x(hu) = 0, \quad \partial_t(hu) + \partial_x(hu^2 + g \frac{h^2}{2}) = \frac{\sigma}{\rho} h \partial_{xxx} h.$$

- Periodic boundary conditions

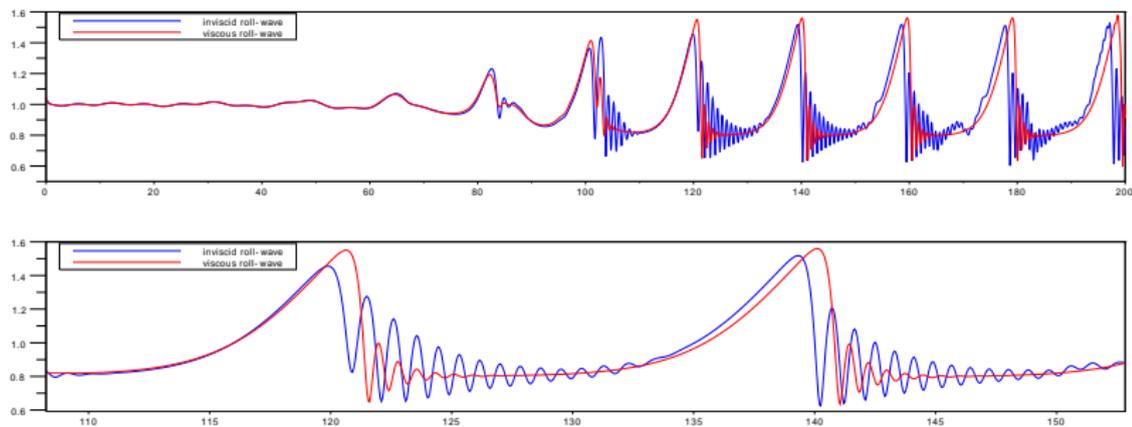


# Entropy stability: numerical comparison II

- Comparison of the original formulation and the “new” formulation
- Second order schemes for numerical simulations
- Conclusion: the new formulation provides a better entropy conservation



# Simulation of Liu Gollub experiment (Phys of Fluids 94)

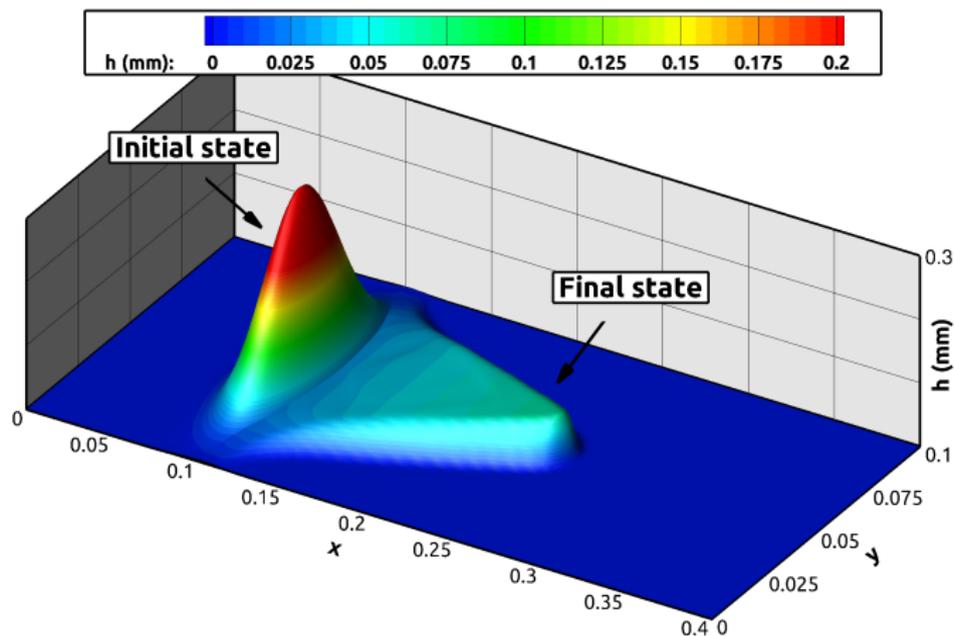


- The viscous term is heuristic
- Numerical scheme: RK2/Rusanov (2nd order) on the extended formulation.
- Reynolds number  $Re = 29$ , Inclination  $\theta = 6.4^\circ$ , Weber number  $We = 35$ .

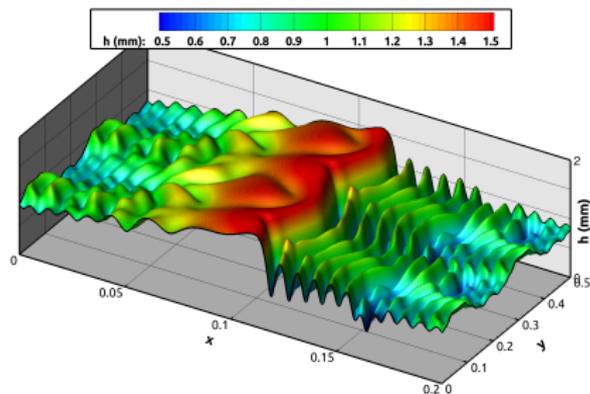
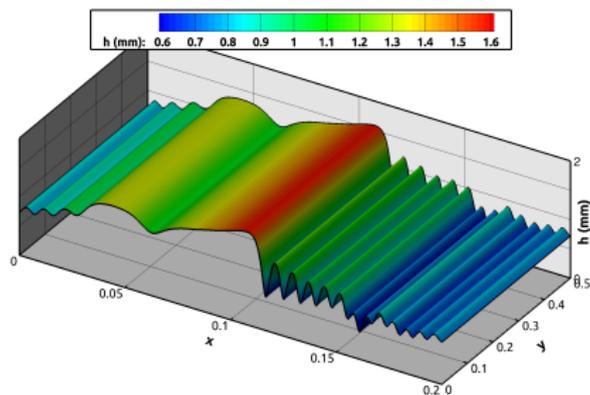
# Numerical Simulations

- Numerical simulation of shallow water equations (consistent models)
- 1d and 2d simulations: IMEx strategies+Extended formulations
- Falling films: roll waves and drop (wet/dry front with precursor film)
- Remark (MUSCL reconstruction): **the flux limiters does not “kill” surface tension effects.**

# Simulation of drop motion



# Simulation of Liu Gollub experiment (Phys of Fluids 94)



# Conclusion

## 1 Summary

- ▶ Proof of entropy stability with a new form of Euler-Korteweg equations
- ▶ Numerically: extended formulation is more stable than original formulation and provides a natural implicit discretization (CFL  $\delta t = O(\delta x)$ ).
- ▶ Ref : Noble Vila SINUM 2014 Vol. 52, No. 6, pp. 2770 2791 and Bresch Couderc Noble Vila <http://arxiv.org/abs/1503.08678>

## 2 Open problems

- ▶ Other dispersive models (water wave models/ bi-fluid models) ?
- ▶ Derivation of suitable boundary conditions?
- ▶ Higher order methods (Discontinuous Galerkin methods)?